## Transformations in the pipeline

ModelView Matrix


## Background (reminder)

## Line (in 2D)

- Explicit

$$
y=\frac{d y}{d x}\left(x-x_{0}\right)+y_{0}
$$

- Implicit
- Parametric

$$
\begin{aligned}
& F(x, y)=\left(x-x_{0}\right) d y-\left(y-y_{0}\right) d x \\
& \text { if } \quad F(x, y)=0 \text { then }(x, y) \text { is on line } \\
& F(x, y)>0 \quad(x, y) \text { is below line } \\
& F(x, y)<0 \quad(x, y) \text { is above line }
\end{aligned}
$$

$$
\begin{gathered}
x(t)=x_{0}+t\left(x_{1}-x_{0}\right) \\
y(t)=y_{0}+t\left(y_{1}-y_{0}\right) \\
t \in[0,1] \\
P(t)=P_{0}+t\left(P_{1}-P_{0}\right), \text { or } \\
P(t)=(1-t) P_{0}+t P_{1}
\end{gathered}
$$

## Background (reminder)

## Plane equations

Implicit
$F(x, y, z)=A x+B y+C z+D=\mathbf{N} \cdot P+D$
Points on Plane $F(x, y, z)=0$

## Parametric

$\operatorname{Plane}(s, t)=P_{0}+s\left(P_{1}-P_{0}\right)+t\left(P_{2}-P_{0}\right)$ $P_{0}, P_{1}, P_{2}$ not colinear
or


Plane $(s, t)=(1-s-t) P_{0}+s P_{1}+t P_{2}$
Plane $(s, t)=P_{0}+s V_{1}+t V_{2}$ where $V_{1}, V_{2}$ basis vectors

## Explicit

$$
z=-(A / C) x-(B / C) y-D / C, C \neq 0
$$

## Reminder: Homogeneous Coordinates

$$
\begin{aligned}
& {\left[\begin{array}{l}
x \\
y \\
z
\end{array}\right] \underset{\sim}{\rightarrow}\left[\begin{array}{c}
w x \\
w y \\
w z \\
w
\end{array}\right]} \\
& {\left[\begin{array}{c}
w x \\
w y \\
w z \\
w
\end{array}\right] \xrightarrow{w} \rightarrow\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right] \rightarrow\left[\begin{array}{l}
x \\
y \\
z
\end{array}\right]}
\end{aligned}
$$

## Projection transformations



## Introduction to Projection Transformations

[Hill: 371-378, 398-404.
Foley \& van Dam: p.
229-242 ]
Mapping: $\mathrm{f}: \mathrm{R}^{\mathrm{n}} \rightarrow \mathrm{R}^{\mathrm{m}}$
Projection: $n>m$
Planar Projection: Projection on a plane.
$R^{3} \rightarrow R^{2}$ or
$R^{4} \rightarrow R^{3}$ homogenous coordinates.


## Basic projections

## Parallel



Perspective


## Taxonomy



## Examples


two-point
perspective


## A basic orthographic projection

$x^{\prime}=x$
$y^{\prime}=y$
$z^{\prime}=N$
Matrix Form

$$
\left[\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 0 & N \\
0 & 0 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]=\left[\begin{array}{c}
x \\
y \\
N \\
1
\end{array}\right]
$$



## A basic perspective projection

## Similar triangles


$x^{\prime} / d=x /(-z) \quad->x^{\prime}=x d /(-z)$
$y^{\prime} / d=y /(-z)=>y^{\prime}=y d /(-z)$
$z^{\prime}=-\mathrm{d}$

## In matrix form

Matrix form of
$x^{\prime}=x d /(-z)$
$y^{\prime}=y d /(-z)$
$z^{\prime}=-d$

$$
\begin{aligned}
& {\left[\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & -1 / d & 0
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]=\left[\begin{array}{c}
x \\
y \\
z \\
-z / d
\end{array}\right]} \\
& {\left[\begin{array}{cccc}
d & 0 & 0 & 0 \\
0 & d & 0 & 0 \\
0 & 0 & d & 0 \\
0 & 0 & -1 & 0
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]=\left[\begin{array}{c}
x d \\
y d \\
z d \\
-z
\end{array}\right]}
\end{aligned}
$$

Moving from 4D to 3D

$$
\left[\begin{array}{c}
x \\
y \\
z \\
-z / d
\end{array}\right] \xrightarrow{h=-z / d}\left[\begin{array}{c}
x / h \\
y / h \\
z / h \\
1
\end{array}\right] \rightarrow\left[\begin{array}{c}
x d /(-z) \\
y d /(-z) \\
-d
\end{array}\right]=\left[\begin{array}{c}
x^{\prime} \\
y^{\prime} \\
z^{\prime}
\end{array}\right]
$$

## Projections in OpenGL

## Camera coordinate system

Image plane = near
plane
Camera at (0,0,0)
Looking at -z
Image plane at $z=-N$


## Perspective projection of a point

In eye coordinates $P=[P x, P y, P z, 1]^{T}$<br>$x / P x=N /(-P z)=>x=N P x /(-P z)$<br>$y / P x=N /(-P z)=>y=N P y /(-P z)$



## Observations

- Perspective foreshortening
- Denominator becomes undefined for $z=0$
- If $P$ is behind the eye Pz changes sign

$$
\begin{aligned}
x^{\prime} & =-N \frac{P_{x}}{P_{z}} \\
y^{\prime} & =-N \frac{P_{y}}{P_{z}} \\
z^{\prime} & =-N
\end{aligned}
$$

- Near plane just scales the picture
- Straight line -> straight line



## Perspective projection of a line

$$
L(t)=\mathbf{A}+\overrightarrow{\mathbf{c}} t=\left[\begin{array}{c}
A_{x} \\
A_{y} \\
A_{z} \\
1
\end{array}\right]+\left[\begin{array}{c}
c_{x} \\
c_{y} \\
c_{z} \\
0
\end{array}\right] t
$$

$$
\widetilde{L}(t)=\mathbf{M} L(t)=\mathbf{M}(\mathbf{A}+\overrightarrow{\mathbf{c}} t)=\mathbf{M}\left[\begin{array}{c}
A_{x}+c_{x} t \\
A_{y}+c_{y} t \\
A_{z}+c_{z} t \\
1
\end{array}\right]=\left[\begin{array}{c}
N\left(A_{x}+c_{x} t\right) \\
N\left(A_{y}+c_{y} t\right) \\
N\left(A_{z}+c_{z} t\right) \\
-\left(A_{z}+c_{z} t\right)
\end{array}\right] \xrightarrow{\text { Perspective Division, }} \begin{aligned}
& \text { drop fourth coordinate }
\end{aligned}
$$

$$
L^{\prime}(t)=\left[\begin{array}{c}
-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\
-N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\
-N
\end{array}\right]
$$

## Is it a line?

Original : $L(t)=\left[\begin{array}{l}x \\ y \\ z\end{array}\right]=\left[\begin{array}{l}A_{x}+c_{x} t \\ A_{y}+c_{y} t \\ A_{z}+c_{z} t\end{array}\right]$
Projected : $L^{\prime}(t)=\left[\begin{array}{l}x^{\prime} \\ y^{\prime} \\ z^{\prime}\end{array}\right]=\left[\begin{array}{c}-N x / z \\ -N y / z \\ -N\end{array}\right]=\left[\begin{array}{c}-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\end{array}\right]$

$$
\begin{aligned}
& x^{\prime}=-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \Rightarrow x^{\prime}\left(A_{z}+c_{z} t\right)=-N\left(A_{x}+c_{x} t\right) \Longrightarrow \\
& x^{\prime} A_{z}+x^{\prime} c_{z} t=-N A_{x}-N c_{x} t \Rightarrow\left\{\begin{array}{c}
x^{\prime} A_{z}+N A_{x}=-\left(x^{\prime} c_{z}+N c_{x}\right) t \\
\text { and similarly for y } \\
y^{\prime} A_{z}+N A_{y}=-\left(y^{\prime} c_{z}+N c_{y}\right) t
\end{array}\right.
\end{aligned}
$$

Cont'd next slide

## Is it a line? (cont'd)

$$
\begin{aligned}
& x^{\prime} A_{z}+N A_{x}=-\left(x^{\prime} c_{z}+N c_{x}\right) t \\
& y^{\prime} A_{z}+N A_{y}=-\left(y^{\prime} c_{z}+N c_{y}\right) t
\end{aligned}\left|\begin{array}{c}
x^{\prime} A_{z}+N A_{x}=-\left(x^{\prime} c_{z}+N c_{x}\right) t \\
-\left(y^{\prime} c_{z}+N c_{y}\right) t=y^{\prime} A_{z}+N A_{y}
\end{array}\right| \Rightarrow \text { (x } \begin{aligned}
& \left.x^{\prime} A_{z}+N A_{x}\right)\left(y^{\prime} c_{z}+N c_{y}\right)=\left(x^{\prime} c_{z}+N c_{x}\right)\left(y^{\prime} A_{z}+N A_{y}\right) \Rightarrow \\
& x^{\prime} A_{z} y^{\prime} c_{z}+x^{\prime} A_{z} N c_{y}+N A_{x} y^{\prime} c_{z}+N^{2} A_{x} c_{y}=x^{\prime} c_{z} y^{\prime} A_{z}+x^{\prime} c_{z} N A_{y}+N c_{x} y^{\prime} A_{z}+N^{2} A_{y} c_{x} \Rightarrow \\
& \left(A_{z} N c_{y}-c_{z} N A_{y}\right) x^{\prime}+\left(N A_{x} c_{z}+N c_{x} A_{z}\right) y^{\prime}+N^{2}\left(A_{x} c_{y}+A_{y} c_{x}\right)=0 \Rightarrow \\
& \Rightarrow \quad a x^{\prime}+b y^{\prime}+c=0 \quad \text { which is the equation of a line. }
\end{aligned}
$$

## So is there a difference?

Original : $L(t)=\left[\begin{array}{l}x \\ y \\ z\end{array}\right]=\left[\begin{array}{l}A_{x}+c_{x} t \\ A_{y}+c_{y} t \\ A_{z}+c_{z} t\end{array}\right]$

Projected : $L^{\prime}(t)=\left[\begin{array}{l}x^{\prime} \\ y^{\prime} \\ z^{\prime}\end{array}\right]=\left[\begin{array}{c}-N x / z \\ -N y / z \\ -N\end{array}\right]=\left[\begin{array}{c}-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\end{array}\right]$

## So is there a difference?

## The speed of the lines if $\mathbf{c z}$ is not 0

Original : $L(t)=\left[\begin{array}{l}x \\ y \\ z\end{array}\right]=\left[\begin{array}{l}A_{x}+c_{x} t \\ A_{y}+c_{y} t \\ A_{z}+c_{z} t\end{array}\right] \Rightarrow \frac{\partial L(t)}{\partial t}=\overrightarrow{\mathbf{c}}$
Projected : $L^{\prime}(t)=\left[\begin{array}{l}x^{\prime} \\ y^{\prime} \\ z^{\prime}\end{array}\right]=\left[\begin{array}{c}-N x / z \\ -N y / z \\ -N\end{array}\right]=\left[\begin{array}{c}-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\ -N\end{array}\right] \Rightarrow$
$\frac{\partial x^{\prime}}{\partial t}=-N \frac{\partial}{\partial t}\left(\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right)\right)=-N \frac{c_{x}\left(A_{z}+c_{z} t\right)-\left(A_{x}+c_{x} t\right) c_{z}}{\left(A_{z}+c_{z} t\right)^{2}}=-N \frac{c_{x} A_{z}-A_{x} c_{z}}{\left(A_{z}+c_{z} t\right)^{2}} \Rightarrow$

$$
\frac{\partial L^{\prime}(t)}{\partial t}=\frac{-N}{\left(A_{z}+c_{z} t\right)^{2}}\left[\begin{array}{l}
c_{x} A_{z}-A_{x} c_{z} \\
c_{y} A_{z}-A_{y} c_{z}
\end{array}\right]
$$

## Inbetween points

## How do points on lines transform?



Viewing system:

$$
R(g)=(1-g) A+g B
$$

Projected (4D) :
Projected cartesian:

$$
r=M R
$$

$$
R^{\prime}(f)=(1-f) A^{\prime}+f B^{\prime}
$$

What is the relationship between g and f ?

## First step

## Viewing to homogeneous space (4D)



## Second step

## Perspective division



$$
\left\{\begin{array}{l}
r=(1-g) a+g b \\
a=\left(a_{1}, a_{2}, a_{3}, a_{4}\right) \\
b=\left(b_{1}, b_{2}, b_{3}, b_{4}\right)
\end{array}\right\} \Rightarrow \quad R_{1}^{\prime}=\frac{r_{1}}{r_{4}}=\frac{(1-g) a_{1}+g b_{1}}{(1-g) a_{4}+g b_{4}}
$$

## Putting all together



$$
R_{1}^{\prime}=\frac{(1-g) a_{1}+g b_{1}}{(1-g) a_{4}+g b_{4}}=\frac{\operatorname{lerp}\left(a_{1}, b_{1}, g\right)}{\operatorname{lerp}\left(a_{4}, b_{4}, g\right)}
$$

At the same time:

$$
R^{\prime}=(1-f) A^{\prime}+f B^{\prime} \Rightarrow R_{1}^{\prime}=(1-f) A_{1}^{\prime}+f B_{1}^{\prime}
$$

$$
R_{1}^{\prime}=(1-f) \frac{a_{1}}{a_{4}}+f \frac{b_{1}}{b_{4}}=\operatorname{lerp}\left(\frac{a_{1}}{a_{4}}, \frac{b_{1}}{b_{4}}, f\right)
$$



## Relation between the fractions

$$
\left.\begin{array}{l}
R_{1}^{\prime}(g)=\frac{\operatorname{lerp}\left(a_{1}, b_{1}, g\right)}{\operatorname{lerp}\left(a_{4}, b_{4}, g\right)} \\
R_{1}^{\prime}(f)=\operatorname{lerp}\left(\frac{a_{1}}{a_{4}}, \frac{b_{1}}{b_{4}}, f \frac{)}{\dot{\dot{j}}}\right.
\end{array}\right\} \Rightarrow g=\frac{f}{\operatorname{lerp}\left(\frac{b_{4}}{a_{4}}, 1, f\right)}
$$

substituting this in $R(g)=(1-g) A+g B$ yields
$R_{1}=\frac{\operatorname{lerp}\left(\frac{A_{1}}{a_{4}}, \frac{B_{1}}{b_{4}}, f\right)}{\operatorname{lerp}\left(\frac{1}{a_{4}}, \frac{1}{b_{4}}, f\right)}$

THAT MEANS: For a given $f$ in screen space and $A, B$ in viewing space we can find the corresponding $R$ (or $g$ ) in viewing space using the above formula.
"A" can be texture coordinates, position, color, normal etc.

## Effect of perspective projection on lines [Hill 375]

## Equations

$$
\begin{aligned}
& \text { Original: } L(t)=\left[\begin{array}{l}
x \\
y \\
z
\end{array}\right]=\left[\begin{array}{l}
A_{x}+c_{x} t \\
A_{y}+c_{y} t \\
A_{z}+c_{z} t
\end{array}\right] \\
& \text { Projected : } L^{\prime}(t)=\left[\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime}
\end{array}\right]=\left[\begin{array}{c}
-N x / z \\
-N y / z \\
-N
\end{array}\right]=\left[\begin{array}{c}
-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\
-N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\
-N
\end{array}\right]
\end{aligned}
$$

What happens to parallel lines?

## Effect of perspective projection on lines [Hill 375]

## Parallel lines

$$
\begin{aligned}
& \text { Original: } L(t)=\left[\begin{array}{l}
x \\
y \\
z
\end{array}\right]=\left[\begin{array}{l}
A_{x}+c_{x} t \\
A_{y}+c_{y} t \\
A_{z}+c_{z} t
\end{array}\right] \\
& \text { Projected: } L^{\prime}(t)=\left[\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime}
\end{array}\right]=\left[\begin{array}{c}
-N x / z \\
-N y / z \\
-N
\end{array}\right]=\left[\begin{array}{c}
-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\
-N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\
-N
\end{array}\right]
\end{aligned}
$$

If parallel to view plane then:

$$
\begin{aligned}
& c_{z}=0 \rightarrow L^{\prime}(t)=-\frac{N}{A_{z}}\left(A_{x}+c_{x} t, A_{y}+c_{y} t\right) \\
& \text { slope }=\frac{c_{y}}{c_{x}}
\end{aligned}
$$

## Effect of perspective projection on lines [Hill 375]

## Parallel lines

$$
\begin{aligned}
& \text { Original: } L(t)=\left[\begin{array}{l}
x \\
y \\
z
\end{array}\right]=\left[\begin{array}{l}
A_{x}+c_{x} t \\
A_{y}+c_{y} t \\
A_{z}+c_{z} t
\end{array}\right] \\
& \text { Projected : } L^{\prime}(t)=\left[\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime}
\end{array}\right]=\left[\begin{array}{c}
-N x / z \\
-N y / z \\
-N
\end{array}\right]=\left[\begin{array}{c}
-N\left(A_{x}+c_{x} t\right) /\left(A_{z}+c_{z} t\right) \\
-N\left(A_{y}+c_{y} t\right) /\left(A_{z}+c_{z} t\right) \\
-N
\end{array}\right]
\end{aligned}
$$

If not parallel to view plane then:
$c_{z} \neq 0 \rightarrow \lim _{t \rightarrow \infty} L^{\prime}(t)=-\frac{N}{c_{z}}\left(c_{x}, c_{y}\right)$
Vanishing point!


## Summary

Forshortening
Non-linear
Lines go to lines
Parallel lines either intersect or remain parallel
Inbetweeness

## Projections in the Graphics Pipeline

## View volumes

- Our pipeline supports two projections:
- Orthographic
- Perspective
- This stage also defines the view window
- What is visible with each projection?
- a cube
- or a pyramid



## View volumes



## Transformation vs Projection

We want to keep z
Why?

- Pseudodepth



## Derivation of the orthographic transformation

Map each axis separately:

- Scaling and translation

Let's look at y:

- $y^{\prime}=a y+b$ such that bottom $\rightarrow-1$ top $\rightarrow 1$


VCS



## Derivation of the orthographic transformation

## Scaling and Translation

$$
y_{V C S} \rightarrow y
$$

$y_{N D C S} \rightarrow y^{\prime}$

$\left(y_{b}, y_{b}^{\prime}\right)=($ bottom, -1) and
$\left(y_{t}, y_{t}^{\prime}\right)=(t o p, 1)$
Line equation $\frac{y^{\prime}-y_{b}^{\prime}}{y-y_{b}}=\frac{y_{t}^{\prime}-y_{b}^{\prime}}{y_{t}-y_{b}}$
$\frac{y^{\prime}-(-1)}{y-\text { bottom }}=\frac{1-(-1)}{\text { top }- \text { bottom }} \rightarrow$
$y^{\prime}=\frac{2}{\text { top }- \text { bottom }} y-\frac{\text { top }+ \text { bottom }}{\text { top }- \text { bottom }}$


## All three coordinates

## Scaling and Translation

Similarly,


$$
\begin{aligned}
x^{\prime} & =\frac{2}{\text { right }- \text { left }} x-\frac{\text { right }+ \text { left }}{\text { right }- \text { left }} \\
y^{\prime} & =\frac{2}{\text { top }- \text { bottom }} y-\frac{\text { top }+ \text { bottom }}{\text { top }- \text { bottom }} \\
z^{\prime} & =\frac{-2}{\text { far }- \text { near }} z-\frac{\text { far }+ \text { near }}{\text { far }- \text { near }}
\end{aligned}
$$



## Matrix form

$$
P^{\prime}=\left[\begin{array}{cccc}
\frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\
0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\
0 & 0 & \frac{-2}{f-n} & -\frac{f+n}{f-n} \\
0 & 0 & 0 & 1
\end{array}\right] P
$$

## Perspective transformation

## Warps the view volume and the objects in it.

- Eye becomes a point at infiinity, and the projection rays become parallel lines (orthographic projection)
- We also want to keep z



## Derivation of the perspective transformation



It is basically a mapping of planes
Normalized view volume is a left handed system!

## Deriving the Matrix


$\left[\begin{array}{c}\widetilde{x} \\ \tilde{y} \\ \widetilde{z} \\ \widetilde{h}\end{array}\right]=\left[\begin{array}{cccc}E & 0 & A & 0 \\ 0 & F & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0\end{array}\right]\left[\begin{array}{c}x \\ y \\ z \\ 1\end{array}\right]$

Top plane:
Before projection $y=-z t / n$
After projection and division $\tilde{y} / \widetilde{h}=1$
From the matrix multiplication:

$$
\begin{aligned}
& \tilde{y}=F y+B z \rightarrow(\text { perspective division }) \\
& \tilde{y} / \tilde{h}=(F y+b z) / \tilde{h} \rightarrow 1=(F y+B z) /(-z) \rightarrow \\
& F t / n-B=1 \quad(1)
\end{aligned}
$$

## Forming the second equation

## From bottom plane

Bottom plane:
$\left[\begin{array}{c}\tilde{x} \\ \tilde{y} \\ \widetilde{z} \\ \tilde{h}\end{array}\right]=\left[\begin{array}{llll}E & 0 & A & 0 \\ 0 & F & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0\end{array}\right]\left[\begin{array}{c}x \\ y \\ z \\ 1\end{array}\right]$

Before projection $y=-z b / n$
After projection and division $\tilde{y} / \tilde{h}=-1$
From the matrix multiplication:

$$
\begin{aligned}
& \tilde{y}=F y+B z \rightarrow(\text { perspective division }) \\
& \tilde{y} / \tilde{h}=(F y+b z) / \tilde{h} \rightarrow-1=(F y+B z) /(-z) \rightarrow \\
& F b / n-B=-1 \quad(2)
\end{aligned}
$$

## Solving the $2 \times 2$ system

## Compute F and B :

$$
\begin{aligned}
& \left\{\begin{array}{c}
\frac{t}{n} F-B=1 \\
\frac{b}{n} F-B=-1
\end{array}\right\} \Rightarrow \begin{array}{c}
F=\frac{2 n}{t-b} \\
B=\frac{t+b}{t-b}
\end{array}
\end{aligned}
$$

## Similarly for $\mathbf{x}$

Compute E and A :

$$
\begin{aligned}
& \left\{\begin{array}{c}
\frac{r}{n} E-A=1 \\
\frac{l}{n} E-A=-1
\end{array}\right\} \Rightarrow \begin{array}{c}
E=\frac{2 n}{r-l} \\
A=\frac{r+l}{r-l}
\end{array}
\end{aligned}
$$

## Similarly z

## Compute C and D

$$
\begin{align*}
& \tilde{z}=C z+D  \tag{1}\\
& \tilde{h}=-z \quad(2)
\end{align*}
$$

Near plane :

$$
\left[\begin{array}{c}
\tilde{x}  \tag{2}\\
\widetilde{y} \\
\widetilde{z} \\
\widetilde{h}
\end{array}\right]=\left[\begin{array}{cccc}
E & 0 & A & 0 \\
0 & F & B & 0 \\
0 & 0 & C & D \\
0 & 0 & -1 & 0
\end{array}\right]\left[\begin{array}{c}
x \\
y \\
z \\
1
\end{array}\right]
$$

$z=-n \rightarrow \frac{\tilde{z}}{\tilde{h}}=\frac{\tilde{z}}{n}=-1$

$$
\begin{equation*}
(1),(2),(3) \rightarrow C(-n) / n+D / n=-1 \tag{3}
\end{equation*}
$$

Similarly for far plane:
$z=f \rightarrow \frac{\tilde{z}}{\tilde{h}}=1$
(1), (2), (5) $\rightarrow C(-f) / f+D / f=1$
$\operatorname{From}(4),(6) \quad C=-(f+n)(f-n), \quad D=-2 f n /(f-n)$

## Putting everything together

$$
\left[\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime} \\
h^{\prime}
\end{array}\right]=\left[\begin{array}{cccc}
\frac{2 n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\
0 & \frac{2 n}{t-b} & \frac{t+b}{t-b} & 0 \\
0 & 0 & -\frac{f+n}{f-n} & -\frac{2 f n}{f-n} \\
0 & 0 & -1 & 0
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]
$$

## Putting everything together

$$
\left[\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime} \\
h^{\prime}
\end{array}\right]=\left[\begin{array}{cccc}
\frac{2 n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\
0 & \frac{2 n}{t-b} & \frac{t+b}{t-b} & 0 \\
0 & 0 & -\frac{f+n}{f-n} & -\frac{2 f n}{f-n} \\
0 & 0 & -1 & 0
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]
$$

Same as orthographic except the scaling and the position of the $x, y$ translation parameters

## Orthographic projection in OpenGL

glMatrixMode(GL_PROJECTION) ;
gILoadldentity() ;
Followed by one of:
glOrtho(left,right,bottom,top,near,far) ;
near plane at $z=-n e a r$
far plane at $z=-f a r$
gluOrtho2D(left,right,bottom,top) ;
assumes near $=0$ far $=1$

## Perspective projection in OpenGL

glMatrixMode(GL_PROJECTION) ;
gILoadIdentity() ;
Followed by one of:
gIFrustrum(left,right,bottom,top,near,far) ; near plane at $z=-n e a r$
far plane at $z=-f a r$
gluPerspective(fovy, aspect,bottom,top) ;
fov measured in degrees and center at 0

Put the code in init or reshape callback.

# Matrix pre-multiplies Modelview matrix 

M = Mproj*CM

## Important

Projection parameters are given in CAMERA Coordinate system (Viewing).

So if camera is at $z=50$ and you give near $=$ 10 where is the near plane with respect to the world?

## Important

Projection parameters are given in CAMERA Coordinate system (Viewing).

So if the camera is at $z=50$ and you give near $=10$ where is the near plane with respect to the world?
Transformed by inverse(Mvcs)

## Nonlinearity of perspective transformation

## Tracks:

Left: $x=-1, y=-1$
Right: $x=1, y=-1$
$Z=-i n f, i n f$
View volume:"
Left $=-1$, right $=1$
Bot $=-1$, top $=1$
Near $=1$, far $=4$


## Comparison of cs's

VCS
X
Y
$Z$
Point
1
-1
Z

## CCS

## NDCS

$$
\begin{array}{ll}
X^{\prime}=E X+A Z & X^{\prime \prime}=X^{\prime} / W^{\prime} \\
Y^{\prime}=F Y+B Z & Y^{\prime \prime}=Y^{\prime} / W^{\prime} \\
Z^{\prime}=C Z+D & Z^{\prime \prime}=Z^{\prime} / W^{\prime} \\
\text { Point' } & \text { Point'" } \\
X^{\prime}=X=1 & X^{\prime \prime}=-1 / Z \\
Y^{\prime}=Y=-1 & Y^{\prime \prime}=1 / Z \\
Z^{\prime}=-5 Z / 3-8 / 3 & Z^{\prime \prime}=5 / 3+8 /(3 Z) \\
W^{\prime}=-Z &
\end{array}
$$

## Z in NDCS vs -Z in VCS

$$
Z^{\prime \prime}=5 / 3+8 /(3 Z)
$$



## Other comparisons

$$
X^{\prime \prime}=-1 / Z \rightarrow Z=-1 / X^{\prime \prime}
$$



## Other comparisons

$$
\begin{aligned}
& X^{\prime \prime}=-1 / Z \\
& Z^{\prime \prime}=5 / 3+8 /(3 Z) \\
& \rightarrow Z^{\prime \prime}=5 / 3-(8 / 3) X^{\prime \prime}
\end{aligned}
$$

## 3D Clipping

## Keep what is visible



## Background (reminder)

## Plane equations

Implicit
$F(x, y, z)=A x+B y+C z+D=\mathbf{N} \cdot P+D$
Points on Plane $F(x, y, z)=0$
Parametric

```
Plane \((s, t)=P_{0}+s\left(P_{1}-P_{0}\right)+t\left(P_{2}-P_{0}\right)\)
\(P_{0}, P_{1}, P_{2}\) not colinear
or
```



Expllfef,$t)=(1-s-t) P_{0}+s P_{1}+t P_{2}$
$\operatorname{Plane}(s, t)=P_{0}+s V_{1}+t V_{2}$ where $V_{1}, V_{2}$ basis vectors

$$
\mathrm{z}=-(\mathrm{A} / \mathrm{C}) \mathrm{x}-(\mathrm{B} / \mathrm{C}) \mathrm{y}-\mathrm{D} / \mathrm{C}, \mathrm{C} \neq 0
$$

## Intersection of line and plane

$$
\vec{N} \cdot\left(P_{a}+t\left(P_{b}-P_{a}\right)\right)+D=0
$$

$$
t=\frac{-D-\vec{N}^{\prime} \cdot P_{a}}{N \cdot P_{b}-\vec{N}^{2} \cdot P_{a}^{\prime}}=\frac{-F\left(P_{a}\right)}{F\left(P_{b}\right)-F\left(P_{a}\right)}
$$

## Orthographic view volume

## Planes

Normals pointing inside
left: $\quad x$ - left $=0$
right: $-x+$ right $=0$
bottom: y - bottom $=0$
top: $-\mathrm{y}+$ top $=0$
front: -z - near =0
back: $\mathrm{z}+\mathrm{far}=0$


## Perspective View volume

## Planes

Normals pointing inside
left: $\quad x+$ left $^{\star} z /$ near $=0$
right: $-x-$ right*z/near $=0$
top: $-y-$ top*z/near $=0$
bottom: y + bottom*z/near $=0$
front: -z - near $=0$
back: $\quad z+$ far $=0$


## Clipping in NDCS

## Normalized view volume

- Constant planes
- Lines in VCS lines NDCS

Problem

- Z coordinate loses its sign



## Clipping in CCS

We'll define the clipping region in CCS by first looking at the clipping region in NDCS:
$-1<=x / w<=1$
This means that in CCS, we have:
-w <= $x<=w$

Similarly for $y, z$

visible
$x=-w$
invisible


## Example

## The perspective transformation creates

W = -z

CCS

unclipped CCS
$\mathrm{P} 1(-2,0,-1,3)$
$\mathrm{P} 2(-3,1,-1,2)$
Typo: they should have different $z$

unclipped NDCS
P1(-0.67,0,-0.33)
$\mathrm{P} 2(-1.5,0.5,-0.5)$
clipped NDCS
P1 ( $-0.67,0,-0.33$ )
$\mathrm{P} 2(-1,0.2,-0.4)$

## Viewport transformation



## Viewport



## Viewport matrix

Scales the $x, y$ to the dimensions of the viewport Scales $z$ to be in $[0,1]$

Matrix form left as an exercise.

## Why viewports?

## Undo the distortion of the projection transformation


aspect ratio 1.0

## Stereo views



## Viewport in OpenGL

## gIViewport(GLint x, GLint y, GLsizei width, GLsizei height) ;

$x, y$ : lower left corner of viewport rectangle in pixels width, height: width and height of viewport.

Put the code in reshape callback.

## Transformations in the pipeline



