

Gaussian and Linear Discriminant Analysis; Multiclass Classification

Professor Ameet Talwalkar

Outline

- 1 Administration
- 2 Review of last lecture
- 3 Generative versus discriminative
- 4 Multiclass classification

Announcements

- Homework 2: due on Wednesday

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- 1 Administration
- 2 Review of last lecture
 - Logistic regression
- 3 Generative versus discriminative
- 4 Multiclass classification

Logistic classification

Setup for two classes

- Input: $\mathbf{x} \in \mathbb{R}^D$
- Output: $y \in \{0, 1\}$
- Training data: $\mathcal{D} = \{(\mathbf{x}_n, y_n), n = 1, 2, \dots, N\}$
- Model of *conditional distribution*

$$p(y = 1|\mathbf{x}; b, \mathbf{w}) = \sigma[g(\mathbf{x})]$$

where

$$g(\mathbf{x}) = b + \sum_d w_d x_d = b + \mathbf{w}^T \mathbf{x}$$

Why the sigmoid function?

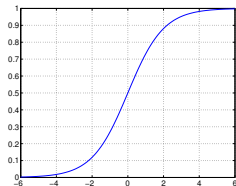
What does it look like?

$$\sigma(a) = \frac{1}{1 + e^{-a}}$$

where

$$a = b + \mathbf{w}^T \mathbf{x}$$

Properties



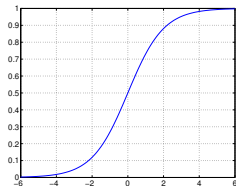
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Properties

- Bounded between 0 and 1 ← thus, interpretable as probability
- Monotonically increasing thus, usable to derive classification rules
 - ▶ $\sigma(a) > 0.5$, positive (classify as '1')
 - ▶ $\sigma(a) < 0.5$, negative (classify as '0')
 - ▶ $\sigma(a) = 0.5$, undecidable
- Nice computational properties Derivative is in a simple form

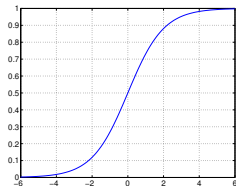
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Linear or nonlinear classifier?

Linear or nonlinear?

$\sigma(a)$ **is nonlinear**, however, the decision boundary is determined by

$$\sigma(a) = 0.5 \Rightarrow a = 0 \Rightarrow g(\mathbf{x}) = b + \mathbf{w}^T \mathbf{x} = 0$$

which is a *linear* function in \mathbf{x}

We often call b the offset term.

Likelihood function

Probability of a single training sample (\mathbf{x}_n, y_n)

$$p(y_n | \mathbf{x}_n; b; \mathbf{w}) = \begin{cases} \sigma(b + \mathbf{w}^T \mathbf{x}_n) & \text{if } y_n = 1 \\ 1 - \sigma(b + \mathbf{w}^T \mathbf{x}_n) & \text{otherwise} \end{cases}$$

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Compact expression, exploring that y_n is either 1 or 0

$$p(y_n | \mathbf{x}_n; b; \mathbf{w}) = \sigma(b + \mathbf{w}^T \mathbf{x}_n)^{y_n} [1 - \sigma(b + \mathbf{w}^T \mathbf{x}_n)]^{1-y_n}$$

Maximum likelihood estimation

Cross-entropy error (negative log-likelihood)

$$\mathcal{E}(b, \mathbf{w}) = - \sum_n \{y_n \log \sigma(b + \mathbf{w}^T \mathbf{x}_n) + (1 - y_n) \log [1 - \sigma(b + \mathbf{w}^T \mathbf{x}_n)]\}$$

Numerical optimization

- Gradient descent: simple, scalable to large-scale problems
- Newton method: fast but not scalable

Numerical optimization

Gradient descent

- Choose a proper step size $\eta > 0$
- Iteratively update the parameters following the negative gradient to minimize the error function

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \eta \sum_n \{ \sigma(\mathbf{w}^T \mathbf{x}_n) - y_n \} \mathbf{x}_n$$

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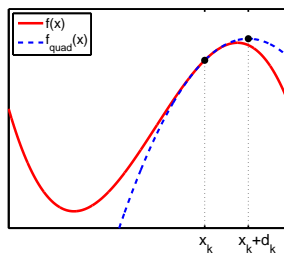
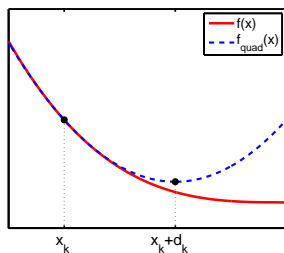
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Remarks

- Gradient is direction of steepest ascent.
- The step size needs to be chosen carefully to ensure convergence.
- The step size can be adaptive (i.e. varying from iteration to iteration).
- Variant called *stochastic* gradient descent (later this quarter).

Intuition for Newton's method

Approximate the true function with an easy-to-solve optimization problem



In particular, we can approximate the cross-entropy error function around $w^{(t)}$ by a quadratic function (its second order Taylor expansion), and then minimize this quadratic function

Update Rules

Gradient descent

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \eta \sum_n \{ \sigma(\mathbf{w}^T \mathbf{x}_n) - y_n \} \mathbf{x}_n$$

Newton method

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \mathbf{H}^{(t)-1} \nabla \mathcal{E}(\mathbf{w}^{(t)})$$

Contrast gradient descent and Newton's method

Similar

- Both are iterative procedures.

Different

- Newton's method requires second-order derivatives (less scalable, but faster convergence)
- Newton's method does not have the magic η to be set

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- 3 Generative versus discriminative**
 - Contrast Naive Bayes and logistic regression
 - Gaussian and Linear Discriminant Analysis
- 4 Multiclass classification

Naive Bayes and logistic regression: two different modelling paradigms

Consider spam classification problem

- First Strategy:

- ▶ Use training set to find a decision boundary in the feature space that separates spam and non-spam emails
- ▶ Given a test point, predict its label based on which side of the boundary it is on.

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- Second Strategy:

- ▶ Look at spam emails and build a model of what they look like. Similarly, build a model of what non-spam emails look like.
- ▶ To classify a new email, match it against both the spam and non-spam models to see which is the better fit.

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First strategy is discriminative (e.g., logistic regression)

Second strategy is generative (e.g., naive bayes)

Generative vs Discriminative

Discriminative

- Requires only specifying a model for the conditional distribution $p(y|x)$, and thus, maximizes the *conditional* likelihood $\sum_n \log p(y_n|\mathbf{x}_n)$.
- Models that try to learn mappings directly from feature space to the labels are also discriminative, e.g., perceptron, SVMs (covered later)

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Generative

- Aims to model the joint probability $p(x, y)$ and thus maximize the *joint* likelihood $\sum_n \log p(\mathbf{x}_n, y_n)$.
- The generative models we'll cover do so by modeling $p(x|y)$ and $p(y)$

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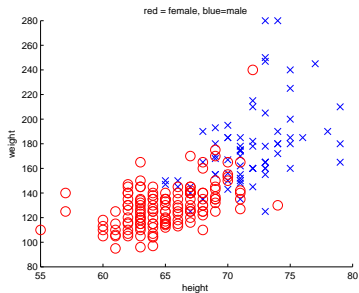
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- The generative models we'll cover do so by modeling $p(x|y)$ and $p(y)$
- Let's look at two more examples: Gaussian (or Quadratic) Discriminative Analysis and Linear Discriminative Analysis

Determining sex based on measurements

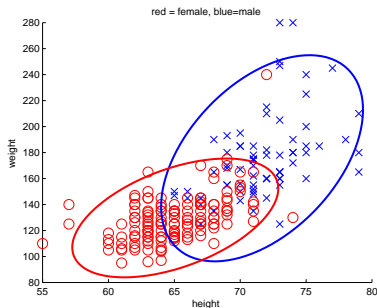


Generative approach

Model joint distribution of $(x = (\text{height, weight}), y = \text{sex})$

our data

Sex	Height	Weight
1	6'	175
0	5'2"	120
1	5'6"	140
1	6'2"	240
0	5.7"	130
...

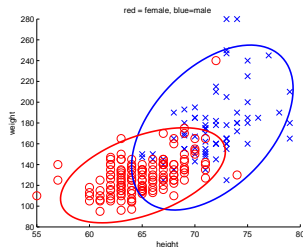


Intuition: we will model how heights vary (according to a Gaussian) in each sub-population (male and female).

Model of the joint distribution (1D)

$$p(x, y) = p(y)p(x|y)$$
$$= \begin{cases} p_0 \frac{1}{\sqrt{2\pi}\sigma_0} e^{-\frac{(x-\mu_0)^2}{2\sigma_0^2}} & \text{if } y = 0 \\ p_1 \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} & \text{if } y = 1 \end{cases}$$

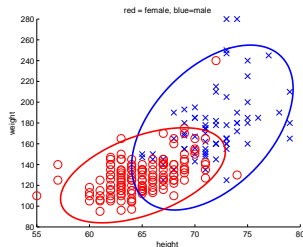
$p_0 + p_1 = 1$ are *prior* probabilities, and $p(x|y)$ is a *class conditional distribution*



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What are the parameters to learn?

Parameter estimation

Log Likelihood of training data $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$ with $y_n \in \{0, 1\}$

$$\begin{aligned}\log P(\mathcal{D}) &= \sum_n \log p(x_n, y_n) \\ &= \sum_{n:y_n=0} \log \left(p_0 \frac{1}{\sqrt{2\pi}\sigma_0} e^{-\frac{(x_n - \mu_0)^2}{2\sigma_0^2}} \right) \\ &+ \sum_{n:y_n=1} \log \left(p_1 \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x_n - \mu_1)^2}{2\sigma_1^2}} \right)\end{aligned}$$

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- For Naive Bayes we assume Σ_i^* is diagonal

Decision boundary

As before, the Bayes optimal one under the assumed joint distribution depends on

$$p(y = 1|x) \geq p(y = 0|x)$$

which is equivalent to

$$p(x|y = 1)p(y = 1) \geq p(x|y = 0)p(y = 0)$$

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Namely,

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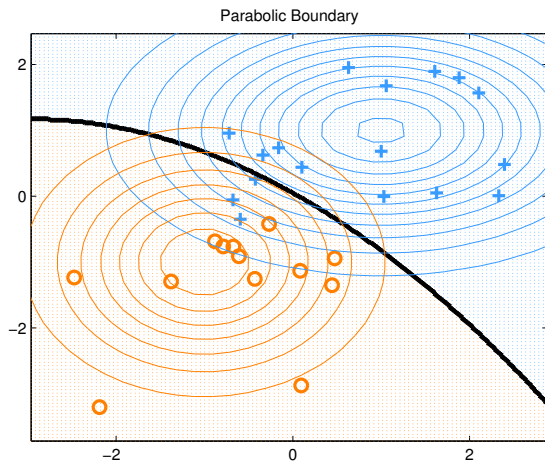
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$$\Rightarrow ax^2 + bx + c \geq 0 \quad \leftarrow \text{the decision boundary not } \textit{linear}!$$

Example of nonlinear decision boundary



Note: the boundary is characterized by a quadratic function, giving rise to the shape of a parabolic curve.

A special case: what if we assume the two Gaussians have the same variance?

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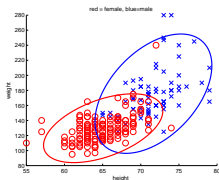
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Note: equal variances across two different categories could be a very strong assumption.



For example, from the plot, it does seem that the *male* population has slightly bigger variance (i.e., bigger ellipse) than the *female* population. So the assumption might not be applicable.

Mini-summary

Gaussian discriminant analysis

- A generative approach, assuming the data modeled by

$$p(x, y) = p(y)p(x|y)$$

where $p(x|y)$ is a Gaussian distribution.

- Parameters (of Gaussian distributions) estimated by max likelihood
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 - ▶ In general, nonlinear functions of x (*quadratic discriminant analysis*)
 - ▶ Linear under various assumptions about Gaussian covariance matrices
 - ★ *Single arbitrary matrix (linear discriminant analysis)*
 - ★ *Multiple diagonal matrices (Gaussian Naive Bayes (GNB))*
 - ★ *Single diagonal matrix (GNB in HW2 Problem 1)*

So what is the discriminative counterpart?

Intuition

The decision boundary in Gaussian discriminant analysis is

$$ax^2 + bx + c = 0$$

Let us model the conditional distribution analogously

$$p(y|x) = \sigma[ax^2 + bx + c] = \frac{1}{1 + e^{-(ax^2+bx+c)}}$$

Or, even simpler, going after the decision boundary of linear discriminant analysis

$$p(y|x) = \sigma[bx + c]$$

Both look very similar to logistic regression — i.e. we focus on writing down the *conditional* probability, *not* the joint probability.

Does this change how we estimate the parameters?

First change: a smaller number of parameters to estimate

Models only parameterized by a , b and c . There are no prior probabilities (p_0, p_1) or Gaussian distribution parameters $(\mu_0, \mu_1, \sigma_0$ and $\sigma_1)$.

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Second change: maximize the conditional likelihood $p(y|x)$

$$(a^*, b^*, c^*) = \arg \min - \sum_n \{y_n \log \sigma(ax_n^2 + bx_n + c)\} \quad (1)$$

$$+ (1 - y_n) \log[1 - \sigma(ax_n^2 + bx_n + c)] \quad (2)$$

No closed form solutions!

How easy for our Gaussian discriminant analysis?

Example

$$p_1 = \frac{\# \text{ of training samples in class 1}}{\# \text{ of training samples}} \quad (3)$$

$$\mu_1 = \frac{\sum_{n:y_n=1} x_n}{\# \text{ of training samples in class 1}} \quad (4)$$

$$\sigma_1^2 = \frac{\sum_{n:y_n=1} (x_n - \mu_1)^2}{\# \text{ of training samples in class 1}} \quad (5)$$

Note: see textbook for detailed derivation (including generalization to higher dimensions and multiple classes)

Generative versus discriminative: which one to use?

There is no fixed rule

- Selecting which type of method to use is dataset/task specific
- It depends on how well your modeling assumption fits the data

Generative versus discriminative: which one to use?

There is no fixed rule

- Selecting which type of method to use is dataset/task specific
- It depends on how well your modeling assumption fits the data
- For instance, as we show in HW2, when data follows a specific variant of the Gaussian Naive Bayes assumption, $p(y|x)$ necessarily follows a logistic function. However, the converse is not true.
 - ▶ Gaussian Naive Bayes makes a stronger assumption than logistic regression
 - ▶ When data follows this assumption, Gaussian Naive Bayes will likely yield a model that better fits the data
 - ▶ But logistic regression is more robust and less sensitive to incorrect modelling assumption

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- 4 Multiclass classification**
 - Use binary classifiers as building blocks
 - Multinomial logistic regression

Setup

Predict multiple classes/outcomes: C_1, C_2, \dots, C_K

- Weather prediction: sunny, cloudy, raining, etc
- Optical character recognition: 10 digits + 26 characters (lower and upper cases) + special characters, etc

Studied methods

- Nearest neighbor classifier
- Naive Bayes
- Gaussian discriminant analysis
- Logistic regression

Logistic regression for predicting multiple classes? Easy

The approach of “one versus the rest”

- For each class C_k , change the problem into binary classification
 - ① Relabel training data with label C_k , into POSITIVE (or ‘1’)
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This step is often called *1-of-K* encoding. That is, only one is nonzero and everything else is zero.

Example: for class C_2 , data go through the following change

$$(\mathbf{x}_1, C_1) \rightarrow (\mathbf{x}_1, 0), (\mathbf{x}_2, C_3) \rightarrow (\mathbf{x}_2, 0), \dots, (\mathbf{x}_n, C_2) \rightarrow (\mathbf{x}_n, 1), \dots,$$

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- Train K binary classifiers using logistic regression to differentiate the two classes

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- Train K binary classifiers using logistic regression to differentiate the two classes
- When predicting on \mathbf{x} , combine the outputs of all binary classifiers
 - ① What if all the classifiers say NEGATIVE?
 - ② What if multiple classifiers say POSITIVE?

Yet, another easy approach

The approach of “one versus one”

- For each *pair* of classes C_k and $C_{k'}$, change the problem into binary classification
 - ① Relabel training data with label C_k , into POSITIVE (or ‘1’)
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- Train $K(K - 1)/2$ binary classifiers using logistic regression to differentiate the two classes
- When predicting on \mathbf{x} , combine the outputs of all binary classifiers
There are $K(K - 1)/2$ votes!

Contrast these two approaches

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Bad about both of them

Combining classifiers' outputs seem to be a bit tricky.

Any other good methods?

Multinomial logistic regression

Intuition: from the decision rule of our naive Bayes classifier

$$\begin{aligned}y^* &= \arg \max_k p(y = C_k | \mathbf{x}) = \arg \max_k \log p(\mathbf{x} | y = C_k) p(y = C_k) \\ &= \arg \max_k \log \pi_k + \sum_i z_i \log \theta_{ki} = \arg \max_k \mathbf{w}_k^T \mathbf{x}\end{aligned}$$

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Essentially, we are comparing

$$\mathbf{w}_1^T \mathbf{x}, \mathbf{w}_2^T \mathbf{x}, \dots, \mathbf{w}_K^T \mathbf{x}$$

with *one* for each category.

First try

So, can we define the following conditional model?

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But we are close!

We can learn the K linear models jointly to ensure this property holds!

Definition of multinomial logistic regression

Model

For each class C_k , we have a parameter vector \mathbf{w}_k and model the posterior probability as

$$p(C_k|\mathbf{x}) = \frac{e^{\mathbf{w}_k^T \mathbf{x}}}{\sum_{k'} e^{\mathbf{w}_{k'}^T \mathbf{x}}} \quad \leftarrow \quad \text{This is called } \textit{softmax} \text{ function}$$

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Decision boundary: assign \mathbf{x} with the label that is the maximum of posterior

$$\arg \max_k P(C_k|\mathbf{x}) \rightarrow \arg \max_k \mathbf{w}_k^T \mathbf{x}$$

How does the softmax function behave?

Suppose we have

$$\mathbf{w}_1^T \mathbf{x} = 100, \mathbf{w}_2^T \mathbf{x} = 50, \mathbf{w}_3^T \mathbf{x} = -20$$

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We would pick the *winning* class label 1.

Softmax translates these scores into well-formed conditional probabilities

$$p(y = 1|\mathbf{x}) = \frac{e^{100}}{e^{100} + e^{50} + e^{-20}} < 1$$

- preserves relative ordering of scores
- maps scores to values between 0 and 1 that also sum to 1

Sanity check

Multinomial model reduce to binary logistic regression when $K = 2$

$$\begin{aligned} p(C_1|\mathbf{x}) &= \frac{e^{\mathbf{w}_1^T \mathbf{x}}}{e^{\mathbf{w}_1^T \mathbf{x}} + e^{\mathbf{w}_2^T \mathbf{x}}} = \frac{1}{1 + e^{-(\mathbf{w}_1 - \mathbf{w}_2)^T \mathbf{x}}} \\ &= \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}} \end{aligned}$$

Multinomial thus generalizes the (binary) logistic regression to deal with multiple classes.

Parameter estimation

Discriminative approach: maximize conditional likelihood

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We will change y_n to $\mathbf{y}_n = [y_{n1} \ y_{n2} \ \cdots \ y_{nK}]^T$, a K -dimensional vector using 1-of- K encoding.

$$y_{nk} = \begin{cases} 1 & \text{if } y_n = k \\ 0 & \text{otherwise} \end{cases}$$

Ex: if $y_n = 2$, then, $\mathbf{y}_n = [0 \ \mathbf{1} \ 0 \ 0 \ \cdots \ 0]^T$.

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Ex: if $y_n = 2$, then, $\mathbf{y}_n = [0 \ \mathbf{1} \ 0 \ 0 \ \cdots \ 0]^T$.

$$\Rightarrow \sum_n \log P(y_n | \mathbf{x}_n) = \sum_n \log \prod_{k=1}^K P(C_k | \mathbf{x}_n)^{y_{nk}} = \sum_n \sum_k y_{nk} \log P(C_k | \mathbf{x}_n)$$

Cross-entropy error function

Definition: negative log likelihood

$$\mathcal{E}(\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_K) = - \sum_n \sum_k y_{nk} \log P(C_k | \mathbf{x}_n)$$

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Properties

- Convex, therefore unique global optimum
- Optimization requires numerical procedures, analogous to those used for binary logistic regression